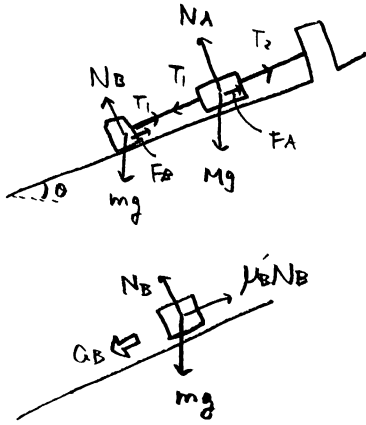


I



$$\begin{cases} NA = Mg \cos \theta \\ T_1 + Mg \sin \theta = F_A + T_2 \end{cases}$$

$$\begin{cases} NB = mg \cos \theta \\ mg \sin \theta = F_B + T_1 \end{cases}$$

(1)  $NA = Mg \cos \theta$

(2)  $T_1 = mg \sin \theta - F_B$

$T_2 = T_1 + Mg \sin \theta - F_A = \underline{(m+M)g \sin \theta - F_A - F_B}$

$$\begin{cases} m a_B = mg \sin \theta - \mu_s' NB \\ NB = mg \cos \theta \end{cases}$$

(3)  $a_B = \underline{g(\sin \theta - \mu_s' \cos \theta)}$

$s = \frac{1}{2} a_B t^2, v_B = a_B t$  (\*)

$v_B = \underline{\sqrt{2gs(\sin \theta - \mu_s' \cos \theta)}}$

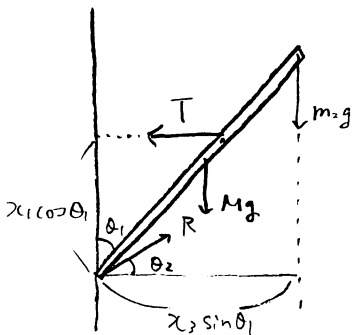
II (4) AとBの間のx-成分のつりあひ

$F_{x1} = m_1 g x_2 + m_2 g x_3$

$F = \frac{(m_1 x_2 + m_2 x_3) g}{x_1}$

(\*)  $F_{x1} = m_1 g x_2 + m_2 g x_3 + Mg \frac{x_3}{2}$

$F = \frac{(M x_3 + 2m_1 x_2 + 2m_2 x_3) g}{2x_1}$



E-x-成分のつりあひ.

$T x_1 \cos \theta_1 = m_2 g x_3 \sin \theta_1 + Mg \cdot \frac{x_3}{2} \sin \theta_1$

力のつりあひ

$$\begin{cases} T = R \cos \theta_2 \\ m_2 g + Mg = R \sin \theta_2 \end{cases}$$

(6)  $T = \underline{\frac{(2m_2 + M) x_3 g \tan \theta_1}{2x_1}}$

$$T = \frac{(2m_2 + 2m_2) \cancel{\lambda} g \tan \frac{\pi}{3}}{\cancel{\lambda} g} = 4m_2 g \times \sqrt{3} = 4\sqrt{3} m_2 g = R \cos \theta_2$$

$$m_2 g + 2m_2 g = R \sin \theta_2 = 3m_2 g$$

$$\frac{\sin \theta_2}{\cos \theta_2} = \frac{\frac{3m_2 g}{R}}{\frac{4\sqrt{3} m_2 g}{R}} = \frac{\sqrt{3}}{4}$$

$$\cos \theta_2 = \frac{4}{\sqrt{16+3}} = \frac{4}{\sqrt{19}}$$

$$R = \frac{4\sqrt{3} m_2 g}{\cos \theta_2} = \underline{\underline{\sqrt{57} m_2 g}}$$

$$\square \text{ I (3)} \quad R_1 \times (1-l_1) = R_2 \times l_1 \quad R_2 = \frac{1-l_1}{l_1} R_1$$

$$(1) \quad E \times \frac{R_2}{R_1+R_2} = \underline{(1-l_1)E}$$

$$(2) \quad E \times \frac{1-l_2}{l_2+(1-l_2)} = \underline{(1-l_2)E}$$

$$(3) \quad R_2, R_3 \text{ の合成抵抗は } \frac{1}{\frac{1}{R_2} + \frac{1}{R_3}} = \frac{R_2 R_3}{R_2 + R_3}$$

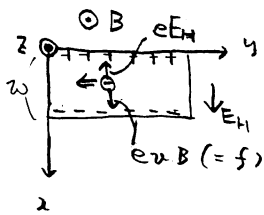
$$R_1 = \frac{R_2 R_3}{R_2 + R_3} = l_2 = 1-l_2 \quad \therefore \frac{R_2 R_3 l_2}{R_2 + R_3} = R_1 (1-l_2)$$

$$R_3 = \frac{(1-l_2) R_1 R_2}{l_2 R_2 - (1-l_2) R_1}$$

$$\text{II (1)} \quad V = I \times \rho \times \frac{l}{hw} \quad \therefore \rho = \frac{hwV}{Il}$$

$$(2) \quad I = envhw \quad \therefore n = \frac{I}{enhw}$$

$$(4) \quad P = I^2 R = VI \quad \therefore \text{熱}$$



$$(1) \quad evB = eE_H = f \quad E_H = \frac{f}{e}$$

$$(2) \quad V_H = E_H w$$

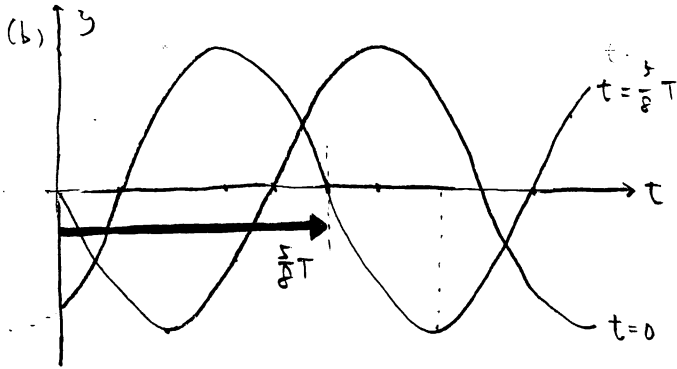
$$(3) \quad F = BIl \quad \text{z軸正の向き}$$

$$\left( \begin{aligned} F &= evB \times nhwl \\ &= Bl \times envhw \\ &= Bl \times I \end{aligned} \right)$$

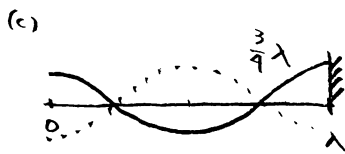
③ (a)  $T = \frac{2\pi}{\omega}$

L の位置で  $\frac{fT}{2}$  だけずれたら  $L = \frac{f}{2}\lambda$   $\lambda = \frac{2}{f}L$

$v = \frac{\lambda}{T} = \frac{2}{f}L \times \frac{\omega}{2\pi} = \frac{4L\omega}{f\pi}$



⑧

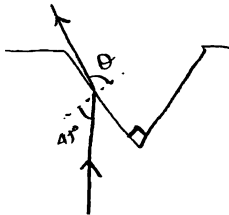


$\lambda = \frac{3}{4}\lambda$   $\frac{3}{4}\lambda$   $\lambda$  の  $\frac{3}{4}$   $\frac{3}{4}\lambda$   $\frac{3}{4}\lambda$   $\frac{3}{4}\lambda$

II (a). スリットの幅が狭いたの光が回折したから.

(e)  $S_0S_1$  と  $S_0S_2$  に 光路差が存在するから.

(f)



$\frac{\sin 45^\circ}{\sin \theta} = \frac{1}{n}$   $\sin \theta = n \sin 45^\circ = \frac{n}{\sqrt{2}} \geq 1$

と  $n \geq \sqrt{2}$  とき 全反射を起す.

$\therefore \underline{n \geq \sqrt{2}}$

④ A:  $PV = nRT$

①  $Q_{AB} = 0 + \frac{3}{2}nR(T_B - T) = \frac{3}{2}nR(2T - T) = \frac{3}{2}nRT$

B  $2P \cdot V = nRT_B \quad T_B = \frac{2PV}{nR} = 2T$

②  $Q_{BC} = 2P(4V - V) + \frac{3}{2}nR(T_C - T_B) = \frac{5}{2}nR(T_C - T_B) = \frac{5}{2}nR(8T - 2T) = 15nRT$

C  $2P \cdot 4V = nRT_C \quad T_C = 8T$

③  $Q_{CD} = 0 + \frac{3}{2}nR(T_D - T_C) = -6nRT$

D  $P \cdot 4V = nRT_D \quad T_D = 4T$

④  $Q_{DA} = P \cdot (4V - V) + \frac{3}{2}nR(T - T_D) = \frac{5}{2}nR(T - T_D) = -\frac{15}{2}nRT$

(あ)  $2T, 8T, 4T$

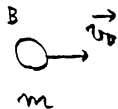
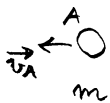
(い) ①

(う)  $Q_1 = Q_{AB} + Q_{BC} = \frac{3}{2}nRT + 15nRT = \frac{33}{2}nRT$

$Q_2 = -Q_{CD} - Q_{DA} = 6nRT + \frac{15}{2}nRT = \frac{27}{2}nRT$

(え)  $e = \frac{Q_1 - Q_2}{Q_1} = \frac{\frac{6}{2}}{\frac{33}{2}} = \frac{2}{11}$

Ⅱ (2.) 運動量, 質量数, 陽子数, 電子数



$$E = (M - 2m)c^2$$

$$\vec{v}_B = -\vec{v}_A$$

運動量が保存いふよ。分裂前の

運動量が 0 だつたから。